

ECON322 Game Theory

Part I Ordinal Payoffs

Topic 2 Dynamic Games with Perfect Information

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Sequential Interactions

- Often interactions are **not simultaneous** but **sequential**.
 - An example is **Chess**, where the two players *White* and *Black* take turns moving pieces on the board.
- Such games are called **Dynamic Games** or **Games in Extensive Form** or **Extensive-Form Games**.
- In **T2** we consider the subclass of **dynamic games with perfect information**.
- The property of **perfect information** states that, whenever it is his turn to move, a player knows **all the preceding moves**.
 - Again **Chess** is an example, as each player entertains **full knowledge of all past moves** throughout the game.
- **Dynamic Games with Perfect Information** can be represented by means of **rooted directed trees**.

Outline

- Formal Structure
- Backward Induction
- Strategies
- Relationship between Backward Induction and Nash Equilibrium

FORMAL STRUCTURE

Trees

Definition 1

A **rooted directed tree** is a pair $\mathcal{T} = \langle X, \Sigma \rangle$, where X is a set of nodes and $\Sigma \subseteq X \times X$ is set of directed edges connecting nodes.

- The **root** of the tree has **no directed edges** leading to it, while every **other node** has **exactly one directed edge** leading to it.
- There exists a **unique path** (i.e. unique sequence of directed edges) leading from the **root** to **any other node**.
- A node that has **no directed edges out of it** is called **terminal node**, while **every other node** is called a **decision node**.
- $X = D \cup Z$, where D is the set of **decision nodes** and Z is the set of **terminal nodes**.

Frames

Definition 2

An **extensive-form frame with perfect information** is a tuple

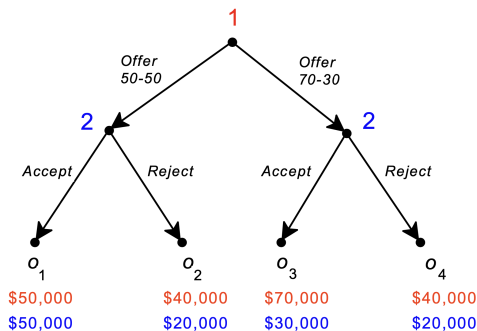
$\mathcal{F}_{PI}^{\mathcal{E}} = \langle \mathcal{T}, I, \alpha_I, A, \alpha_A, O, \alpha_O \rangle$, where

- \mathcal{T} is a **rooted directed tree**.
- I is a set of **players** and $\alpha_I : X \rightarrow I$ is a function assigning exactly one player to every decision node.
- A is a set of **actions** and $\alpha_A : \Sigma \rightarrow A$ is a function assigning exactly one action to every directed edge such that no two edges of the same node receive the same action.
- O is a set of **outcomes** and $\alpha_O : Z \rightarrow O$ is a function assigning exactly one outcome to every terminal node.

Illustration

- Alice (Player 1) and Bob (Player 2) have decided to dissolve a business partnership whose assets have been valued at \$100k.
- According to their charter, the senior partner, Alice, makes an offer about the assets division to the junior partner, Bob.
- The junior partner can
 - *Accept*, in which case the proposal is implemented,
 - *Reject*, in which case the division goes to litigation.
- A litigation costs \$20k in legal fees per partner while the typical verdict assigns \$60k to the senior and \$40k to the junior partner.
- For simplicity sake: there is no uncertainty about the verdict and Alice can only propose two possible offers: 50-50 or 70-30 splits.

Representation as an Extensive Form Frame with Perfect Information



Games

Definition 3

An **extensive-form game with perfect information** is a tuple

$\mathcal{G}_{PI}^{\mathcal{E}} = \langle \mathcal{F}_{PI}^{\mathcal{E}}, (\succsim_i)_{i \in I} \rangle$, where

- $\mathcal{F}_{PI}^{\mathcal{E}}$ is an **extensive form frame with perfect information**.
- \succsim_i is a complete and transitive preference relation over O for every player $i \in I$.

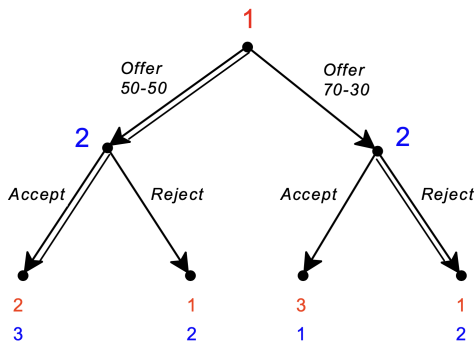
Illustration

- Assume that **Alice** is **self-interested**, while **Bob** is above all concerned with **fairness**, giving rise to the following **rankings**:
 - $o_3 \succ_1 o_1 \succ_1 o_2 \sim_1 o_4$
 - $o_1 \succ_2 o_2 \sim_2 o_4 \succ_2 o_3$

- These **preferences** can be represented by means of **ordinal utility functions** $U_i : O \rightarrow \mathbb{R}$ for $i \in \{1, 2\}$, e.g.:
 - $U_1(o_1) = 2$ and $U_1(o_2) = U_1(o_4) = 1$ and $U_1(o_3) = 3$
 - $U_2(o_1) = 3$ and $U_2(o_2) = U_2(o_4) = 2$ and $U_2(o_3) = 1$

- The **outcomes** in the previous **extensive-form frame** can then be replaced by a corresponding **pair of utilities**.

Reasoning about the Ensuing Extensive Form Game



BACKWARD INDUCTION

Towards A Solution Concept for Finite Dynamic Games with Perfect Information

Definition 4

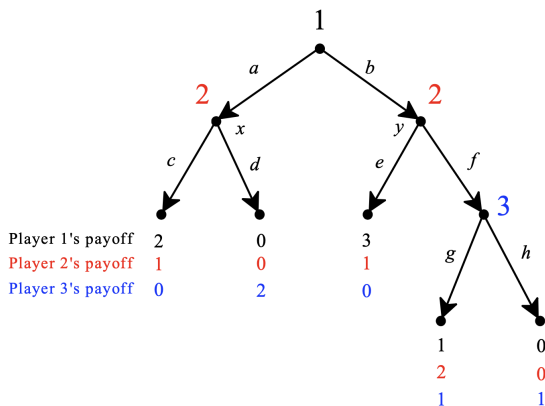
Let $\mathcal{G}_{PI}^{\mathcal{E}}$ be a finite extensive-form game with perfect information. The following marking procedure is called **Backward Induction**:

- 1 Let every terminal node $z \in Z$ be called marked.
- 2 Select a decision node $x \in X$ whose immediate successors are all marked. Let $i \in I$ be the player who moves at x . Select a choice $a \in A$ that leads to an immediate successor of x with the highest utility (among the immediate successors of x) for i . Mark x with the utility vector associated with the node that follows a .
- 3 Repeat step 1 until every decision node $x \in X$ has been marked.

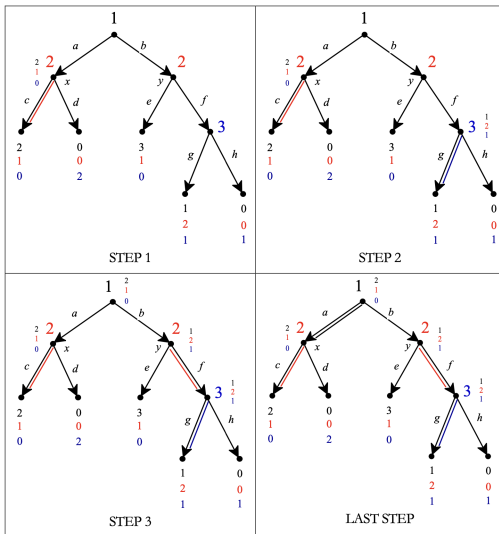
Some Comments on Backward Induction

- By the assumption of **finiteness**, the procedure of **Backward Induction** is well-defined.
- In general, at a decision node there **may** be **several choices** that **maximize** the **utility** of the moving player at that node.
 - In that case **Backward Induction** requires that **one such choice** be selected.
 - This arbitrary selection may lead to the existence of **multiple solutions** in line with **Backward Induction**.

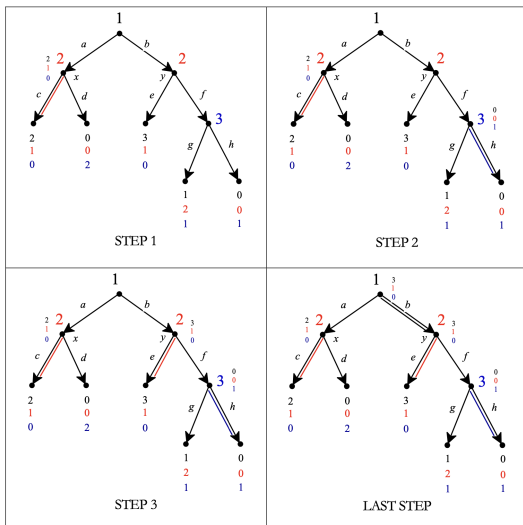
Illustration



Possibility 1



Possibility 2



Ways to graphically implement Backward Induction

- At every step, the **selected choices** are shown by **double edges**.
- In the previous figures the **node marking** is done **explicitly**, but a more **succint** approach **merely highlights** the **selected choices**.

STRATEGIES

Objects of Choice in Dynamic Games

- A **strategy** for a player in a **dynamic game** is a **complete, contingent plan** on how to act in any situation that may emerge.
- Formally:

Definition 5

Let $\mathcal{G}_{PI}^{\mathcal{E}}$ be an extensive-form game with perfect information and $i \in I$ some player. A **strategy** for i is a tuple of choices, which contains one choice for each of i 's decision nodes. The set of all strategies of i is denoted by S_i .

Illustration

■ For example, suppose that **Alice** has three decision nodes:

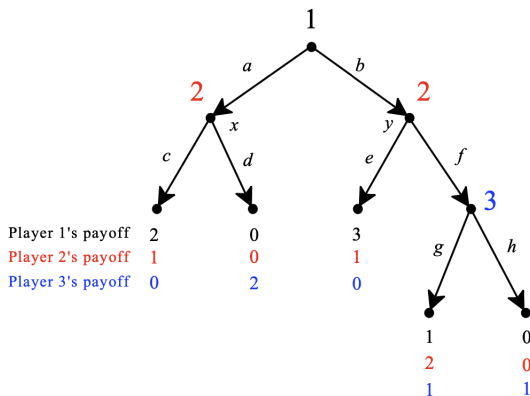
- at node a she has three possible choices a_1, a_2, a_3 ,
- at node b she has two possible choices b_1, b_2 ,
- at node c she has four possible choices c_1, c_2, c_3, c_4 ,

■ A **strategy** can be thought of as a way of filling in three blanks:

$$\left(\underbrace{\quad\quad\quad}_{\text{one of } a_1, a_2, a_3}, \quad \underbrace{\quad\quad\quad}_{\text{one of } b_1, b_2}, \quad \underbrace{\quad\quad\quad}_{\text{one of } c_1, c_2, c_3, c_4} \right)$$

■ In total, there are thus $3 \times 2 \times 4 = 24$ possible strategies for **Alice**.

Illustration



- $S_1 = \{(a), (b)\}$
- $S_2 = \{(c, e), (c, f), (d, e), (d, f)\}$
- $S_3 = \{(g), (h)\}$

Interpretational Remarks

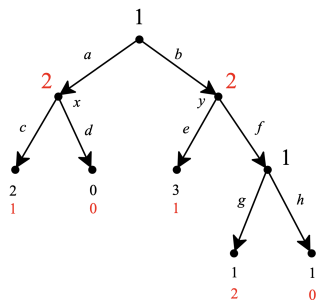
- The notion of **strategy** involves **redundancies**.
- Indeed, a player is required to **plan** for nodes that are **excluded** by his **own earlier choices**.
- Possible **justifications**:
 - A player is **so cautious** that he wants his plan to also cover the possibility of making a **mistake** in implementing his plan.
 - A strategy as a **set of instructions** to a third party; thus the player may indeed worry about **implementation mistakes**.
 - A strategy as a **belief** in the mind of the **opponents** about what the player would do.

Strategic Form of a Dynamic Game

- For every dynamic game it is possible to construct a corresponding **strategic-form game**.
- A **strategy profile** determines a **unique terminal node** reached if the players act accordingly and thus a **unique utility vector**.
- Indeed, a set of **players**, a set of **strategies** for every player, and a **utility function** for every player define a game in **strategic form**.
- Because of the discussed **redundancies** above, the **strategic form** of a **dynamic game** can also display **redundancies**.
(*“identical rows or identical columns”*)
- The **strategic-form game** corresponding to a given **dynamic game** $\mathcal{G}_{PI}^{\mathcal{E}}$ can be denoted by $\mathcal{R}(\mathcal{G}_{PI}^{\mathcal{E}})$.

Illustration

Consider the following **Extensive Form**...



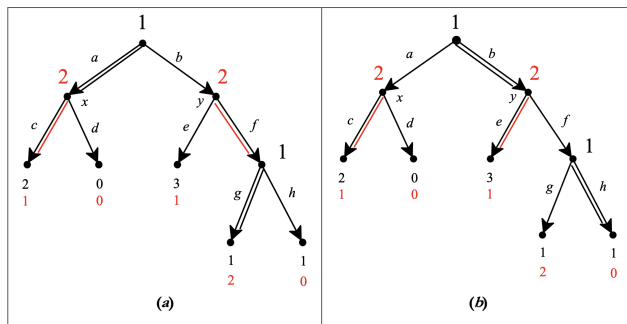
...its corresponding **Strategic Form** is

		2			
		(c,e)	(c,f)	(d,e)	(d,f)
1	(a,g)	2, 1	2, 1	0, 0	0, 0
	(a,h)	2, 1	2, 1	0, 0	0, 0
	(b,g)	3, 1	1, 2	3, 1	1, 2
	(b,h)	3, 1	1, 0	3, 1	1, 0

Formulating Backward Induction in terms of Strategies

- From the definition of **Backward Induction** it follows that the procedure selects a **unique choice** at every decision node.
- Consequently, **Backward Induction** yields a **strategy profile** for the entire game.
- The **output** of the solution concept **Backward Induction** is typically denoted as BI and note that $BI \subseteq \times_{i \in I} S_i$ holds.

Illustration



(a) $\{((a, g), (c, f))\} \in BI$

(b) $\{((b, h), (c, e))\} \in BI$

RELATIONSHIP BETWEEN BACKWARD INDUCTION AND NASH EQUILIBRIUM

Backward Induction implies Nash Equilibrium

Theorem 6

Let $\mathcal{G}_{PI}^{\mathcal{E}}$ be an extensive-form game with perfect information. Consider the corresponding strategic-form game $\mathcal{R}(\mathcal{G}_{PI}^{\mathcal{E}})$. Then, $BI \subseteq NE$.

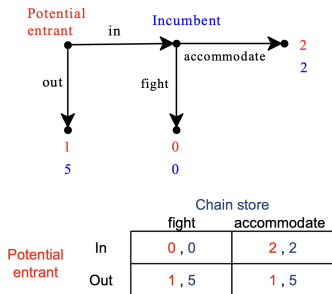
Proof of Theorem 6

- Towards a contradiction, suppose that there exists $s^* \in \times_{i \in I} S_i$ such that $s^* \in BI$ but $s^* \notin NE$ in the strategic-form game $\mathcal{R}(\mathcal{G}_{PI}^E)$.
- Then, there exists some player $i \in I$ such that s_i^* is not a best response to s_{-i}^* , i.e. there exists some strategy $s'_i \in S_i$ such that $\pi_i(s'_i, s_{-i}^*) > \pi_i(s_i^*, s_{-i}^*)$.
- Consequently, applied to \mathcal{G}_{PI}^E , the strategy $s'_i \in S_i$ leads to a terminal node with higher utility than s_i^* fixing the opponents' choices throughout the tree in line with s_{-i}^* .
- It follows that s_i^* does not prescribe optimal choices at all of i 's decision nodes given the opponents' choices prescribed at all other decision nodes according to s_{-i}^* .
- Therefore, $s^* \notin BI$, which is a contradiction.

Incredible Threats

- **Nash Equilibria** that are **not backward inductive** often involve **incredible threats**.
- To see this, consider the so-called **Entry Game**.
- An industry is currently a **monopoly** and the **incumbent** is making a profit of \$5m, while a **potential entrant** is thinking about entry.
 - In the case of **staying out**, another investment yields \$1m.
 - In the case of **entering**, the **incumbent** can **fight** with a price war resulting in both firms making zero profits.
 - Alternatively, the **incumbent** can **accommodate** by sharing the market resulting in both firms making \$2m.
- It is assumed that both firms care about their **own profits** only.

The Entry Game



		Chain store	
		fight	accommodate
Potential entrant	In	0, 0	2, 2
	Out	1, 5	1, 5

(a) $BI = \{(in, accommodate)\}$

(a) $NE = \{((in, accommodate), (out, fight))\}$

The Entry Game

- In fact, the **NE** (*out, fight*) involves an **incredible threat** on the part of the **incumbent**, namely to **fight** if entry occurs.
- If the **potential entrant** believes the threat, then he is better off staying out, however he should **ignore the threat**.
- Indeed – when faced with the **fait accompli** of entry – the **incumbent** would not want to carry out the threat.
- **BI** filters out the “**more plausible solution**” in the **Entry Game**.
- In general, **BI** can be seen as a **refinement** of **NE**.

Background Reading

GIACOMO BONANNO (2018): *Game Theory*, 2nd Edition

- Chapter 3: **Perfect-Information Games**

available at:

http://faculty.econ.ucdavis.edu/faculty/bonanno/GT_Book.html